**Bond University Research Repository** 



#### Mixed reality in higher education: Pedagogy before technology

Birt, James R.; Cowling, Michael A

Licence: CC BY-SA

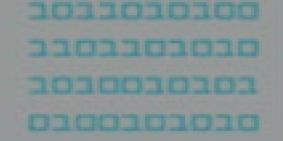
Link to output in Bond University research repository.

Recommended citation(APA): Birt, J. R., & Cowling, M. A. (2016). *Mixed reality in higher education: Pedagogy before technology*. Australian Learning Analytics Summer Institute Workshop, Adelaide , South Australia, Australia.

#### General rights

Copyright and moral rights for the publications made accessible in the public portal are retained by the authors and/or other copyright owners and it is a condition of accessing publications that users recognise and abide by the legal requirements associated with these rights.

For more information, or if you believe that this document breaches copyright, please contact the Bond University research repository coordinator.



### Mixed Reality in Higher Education: Pedagogy Before Technology

2016 Australian Learning Analytics Summer Institute Workshop

Dr James Birt Bond University Dr Michael Cowling CQUniversity

Ð

SB

### Mixed Reality in Higher Education: Workshop Summary

Topic	Duration (minutes)
Welcome, introductions & housekeeping	5
Future Proof: future jobs, skills & why mixed reality	15
Mixed reality hands on: featuring three (3) case studies	25
Break	5
Heart MR: simulation + learning analytics breakdown	30
Pedagogy before technology & lessons learned	10
Concept mapping a mixed reality pedagogy pilot study – from learning outcomes to applied simulation	25
Workshop conclusion & feedback survey	5



### www.bond.edu.au/profile/dr-james-birt



### The pen is mightier than the sword, but the computer is mightier than both



### <u>www.michaelacowling.com</u>

WARDS

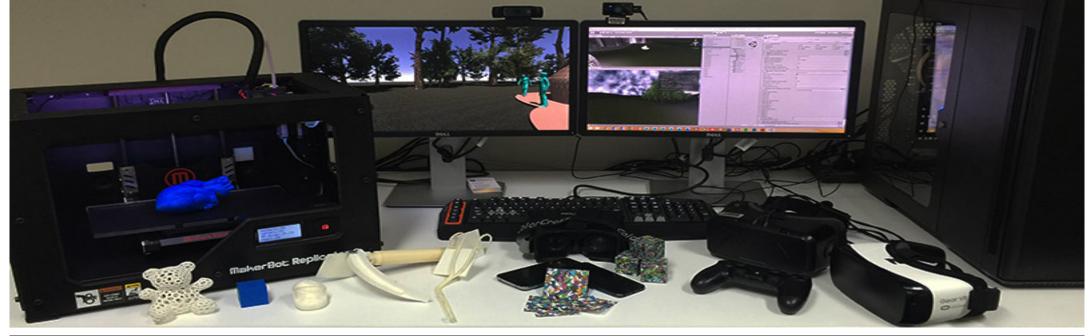


February 12, 2015 4,00pm AEDT

Department of Education and Training **2016** Australian Awards for University Teaching Citations for Outstanding Contributions to Student Learning Pr Michael Convints Pr

Australian Govern





### www.mixedrealityresearch.com

**Spatial Design** 

**Paramedics Skills** 

**Anatomy Education** 



**Network Modeling** 







Merging physical and virtual worlds through virtual reality, augmented reality, 3d printing & game technology



### The Future of Jobs

- 4<sup>th</sup> Industrial Revolution
- Developments in AI, robotics, visualization, nanotechnology, 3-D printing, genetics & biotechnology
- Widespread disruption to business & labour markets worldwide – automation + technology
- 40% of current jobs gone in 10 years → primary disruption white collar jobs!

<u>Watch Future Proof – Four Corners ABC</u>

#### TOMORROW'S DIGITALLY ENABLED WORKFORCE



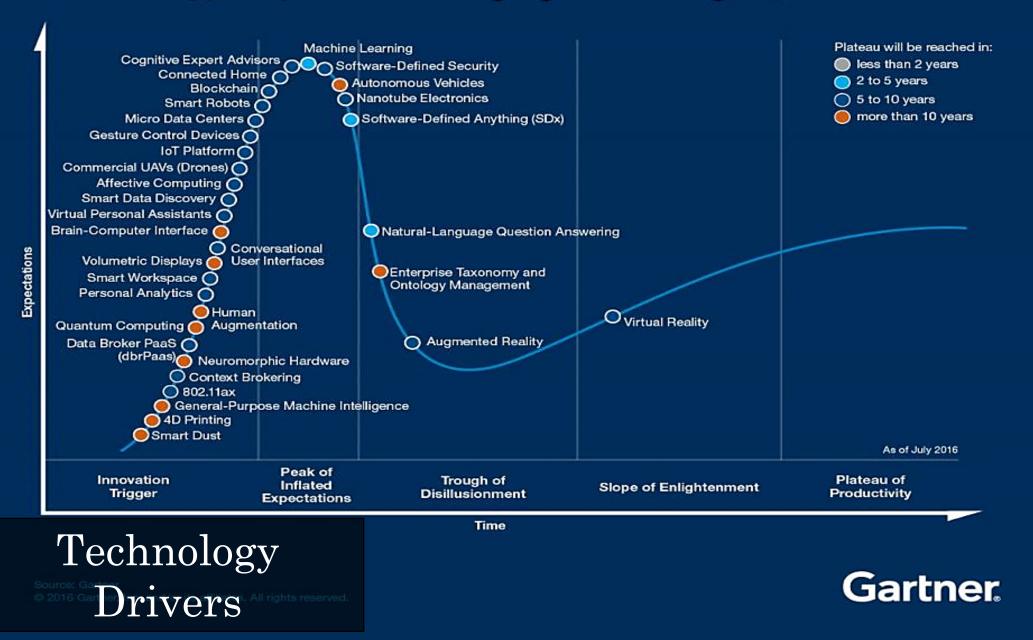
<u>Tomorrows Digitally Enabled</u> <u>Workforce</u>

The industrial revolution's next wave

Nathan Taylor CEDA Chief Economist

Ceda Workforce Policy 2015

#### Gartner Hype Cycle for Emerging Technologies, 2016



"most of the job titles will be the same as today ... we will still have carpenters, nurses, road repairers, even teachers ... but the nature of what they do and the skills they need will change ... just as they have over the past 20 years"

Ron Johnston Executive Director, Australian Centre for Innovation, University of Sydney Are you ready for <u>The Conversation (Aug 2, 2016)</u>

August 2, 2016 2.28pm AES

#### Abilities

### **Basic Skills**

### **Cross-functional Skills**

#### **Cognitive Abilities**

- » Cognitive Flexibility
- » Creativity
- » Logical Reasoning
- » Problem Sensitivity
- » Mathematical Reasoning
- » Visualization

#### Content Skills

- » Active Learning
- » Oral Expression
- » Reading
- Comprehension
- » Written Expression
- » ICT Literacy

#### **Social Skills**

- » Coordinating with Others
- » Emotional Intelligence
- » Negotiation
- » Persuasion
- » Service Orientation
- » Training and Teaching Others

#### Resource Management Skills

- » Management of
- **Financial Resources**
- » Management of Material Resources
- » People Management
- » Time Management

#### **Physical Abilities**

» Physical Strength

WØRLD ECØNOMIC

FORUM

» Manual Dexterity and Precision

#### **Process Skills**

- » Active Listening
- » Critical Thinking
- » Monitoring Self and Others

#### Systems Skills » Judgement and Decision-making

» Systems Analysis

### Technical Skills

- » Equipment Maintenance and Repair
- » Equipment Operation and Control
- » Programming
- » Quality Control
- » Technology and User Experience Design
- » Troubleshooting

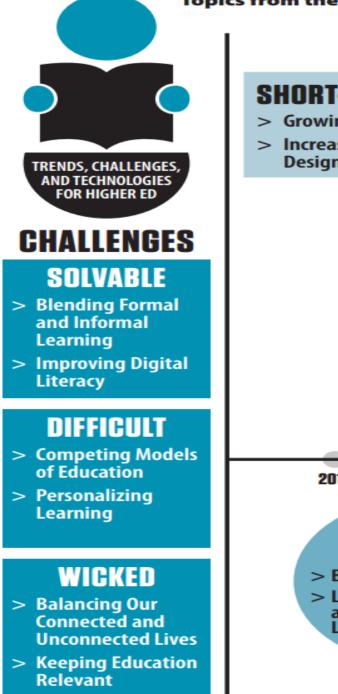
1

### <u>2016 – The Future of</u> <u>Jobs Report - Core</u> <u>work skills</u>

#### Complex Problem Solving Skills

» Complex Problem Solving





#### TRENDS

#### SHORT-TERM IMPACT

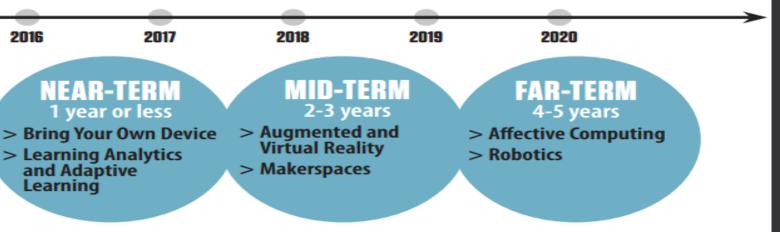
- > Growing Focus on Measuring Learning
- > Increasing Use of Blended Learning Designs

#### **MID-TERM IMPACT**

- > Redesigning Learning Spaces
- > Shift to Deeper Learning Approaches

#### LONG-TERM IMPACT

- > Advancing Cultures of Innovation
- > Rethinking How Institutions Work



#### **DEVELOPMENTS IN TECHNOLOGY**

NMC Horizon Report 2016 Higher Education Edition	2016 Technology Outlook for Australian Tertiary Education	2015 Technology Outlook for Australian Tertiary Education				
Tim	Time-to-Adoption Horizon: One Year or Less					
Bring Your Own Device	Bring Your Own Device	Bring Your Own Device				
Flipped Classroom	Flipped Classroom	Cloud Computing				
Learning Analytics/Adaptive	Learning Analytics	Flipped Classroom				
Online Learning	Online Learning	Learning Analytics				
Time-to-Adoption Horizon: Two to Three Years						
3D Printing	Adaptive Learning Technologies	Badges/Microcredit				
Augmented/Virtual Reality	Location Intelligence	Mobile Learning				
Makerspaces	Makerspaces	Open Licensing				
Wearable Technology	Wearable Technology	wearable Technology				
Time	e-to-Adoption Horizon: Four to Five Y	'ears				
Affective Computing	Affective Computing	Adaptive Learning Technologies				
Next-Generation Batteries	Augmented Reality	Augmented Reality				
Quantified Self	Machine Learning	Quantified Self				
Robotics	Networked Objects	Telepresence				



### 2016 NMC Technology Outlook Australian Tertiary Education

A Horizon Project Regional Report

"this course is a 'skills' learning course ... there should be a way for us to actually get more time doing skills ... distance students at a severe disadvantage ... I am missing out ... you can read about the skills but its impossible to get feedback and to know if you're doing it right ... no substitution for experience ... any software or equipment to at least go through the motions of doing the skills?"

Sample - Student Evaluations

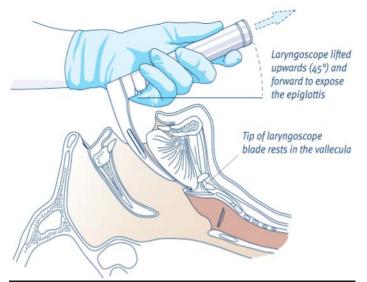


### Background Research

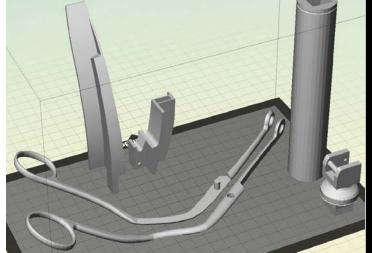
- Difficult to teach complex processes without real world models (Tasker & Dalton, 2008)
- Traditional teaching methods often use abstract visualizations but don't capture complexity (Williamson et al., 2012)
- Focus on technology enhanced T&L (Johnson et al., 2016; Keppell et al., 2011)
- Visualizations are positive learning support tools (Mayer, 2014; Höffler, 2010)
- Kinaesthetic tools better form mental models (Pass & Sweller, 2014)

Most prior work in (multimedia...blended...dual modality) learning has been formed around words & pictures with less attention to complex learning environments such as interactive visualisations, games & simulations (Ayres, 2015)

### Case Study: Mixed Reality Simulation in Paramedic Distance Education



Traditional Teaching Method



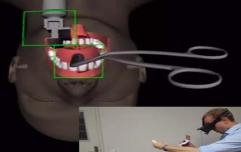




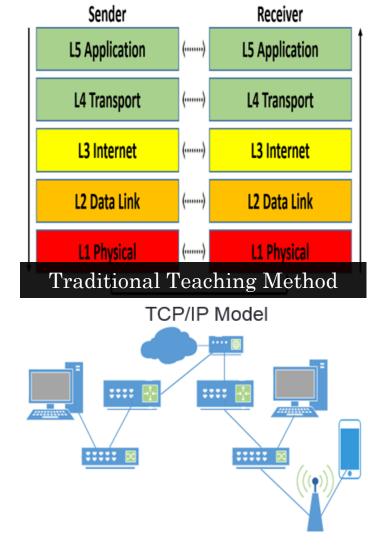


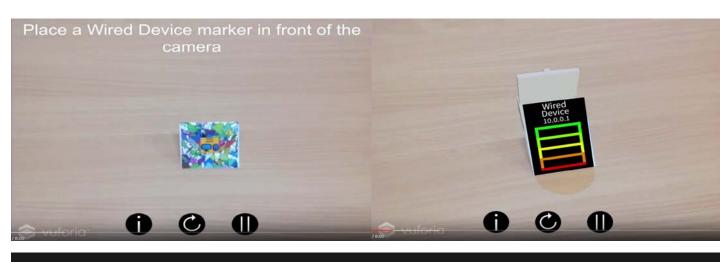


Remove Forceps and Foreign Body While Keeping Within the Green Guide

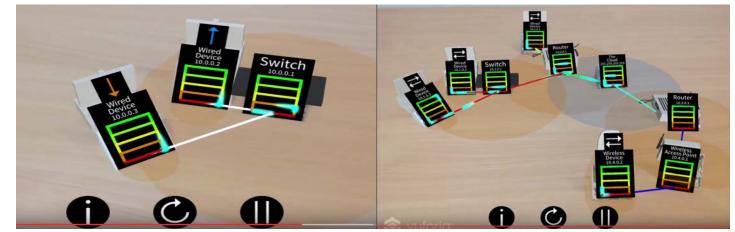


### Case Study: Mixed Reality in ICT Networking to Visualize Complex Theoretical Multi-Step Problems

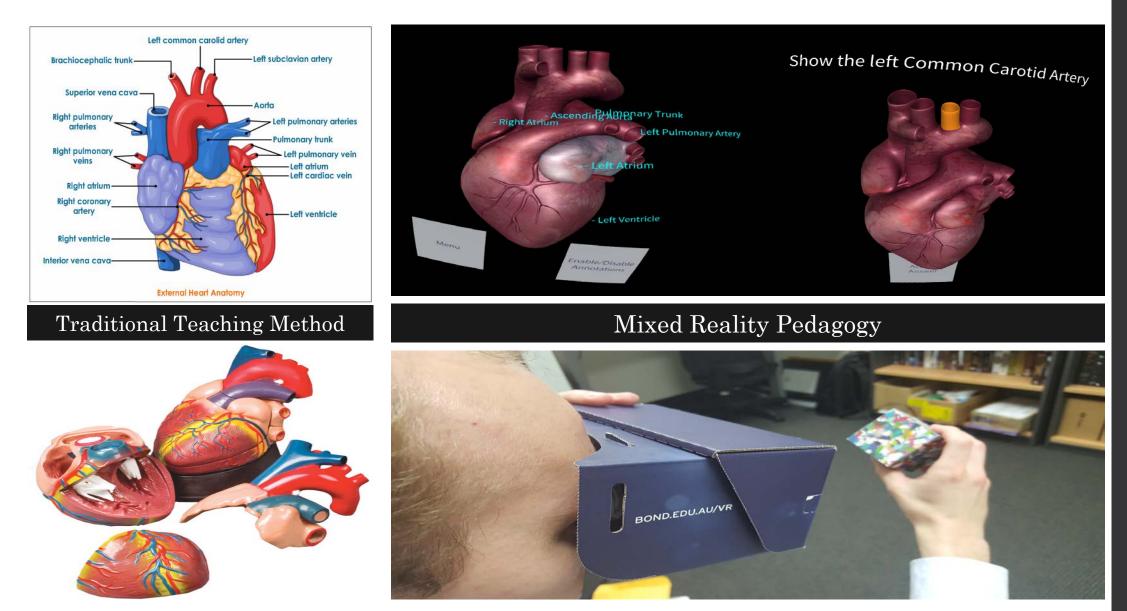




#### Mixed Reality Pedagogy



### Case Study: Mixed Reality and Spatial Learning Analytics to Facilitate Learning of Anatomy



### Hands-On

- $\rightarrow$  Take some time to explore the three (3) case studies
- <u>Paramedics app</u> available on google play and IOS app store search 'Laryngoscopy AR' – requires a head mounted google cardboard device
- <u>Networking app</u> available on google play and IOS app store search 'Networking AR' – can be used on any phone or tablet device
- Heart MR → currently available via phones in the room or built to your android device (only)
- Tools & markers are available in the room

If you download an app and want to use it later, all markers and 3d printable files are available at <u>www.mixedrealityresearch.com</u>

Mixed Reality in Higher Education: Pedagogy Before Technology - Visualisation Feedback Survey						
Visualisation: Paramedics    Networking				Α	nato	my
QUESTIONS (Please cross the most appropriate response) - Likert Scale	1-	5 - u	se O	for I	N/A	
Accessibility: being accessible or available for use	0	1	2	3	4	5
Learnability: allowing accomplishment of the learning objective	0	1	2	3	4	5
Cost: affordability in terms of monetary cost or efficiency in terms of time	0	1	2	3	4	5
Satisfaction: providing confidence in meeting the learning objective	0	1	2	3	4	5
Memorability: effectiveness or ease of re-establishing proficiency of the earning objective after a period (length) of time (past activities)	0	1	2	3	4	5
Usability: responsiveness, robustness, stability or errors in use (e.g. motion sickness, frame rates, bugs)	0	1	2	3	4	5
Manipulability: allowing interactive variable manipulation e.g. rotation, time, scene objects, etc.	0	1	2	3	4	5
Navigability: allowing spatial translation of the viewpoint				3	4	5
Visibility: providing a clear interface design to observe (vision) and interpret the learning objective				3	4	5
Fidelity: providing an accurate representation of the real world (including visual, touch and sound)	0	1	2	3	4	5
Communication: supporting discussion of learning objectives between stakeholders (instructor, learners, others)	0	1	2	3	4	5
Creativity: allowing emergent, creative, playful discovery towards the earning objectives	0	1	2	3	4	5
Engagement: novelty, aesthetics, or feedback to focus learner attention and involvement on the learning objective	0	1	2	3	4	5
Motivation: wanting to complete the learning objective	0	1	2	3	4	5
Additional Comments						

Getting to the HEART of Blended Learning

**Case Stud** 

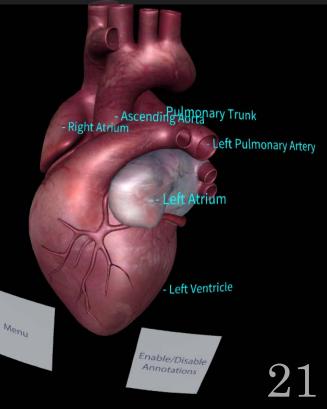
Stirling, A., & <u>Birt, J.</u> (2014). An enriched multimedia eBook application to facilitate learning of anatomy. *Anatomical sciences education*, 7(1), 19-27.

# Heart MR → Breakdown

Capture learner <> mixed reality material interaction(s) and learning outcomes



Follow up Study – Using Mixed Reality + Analytics

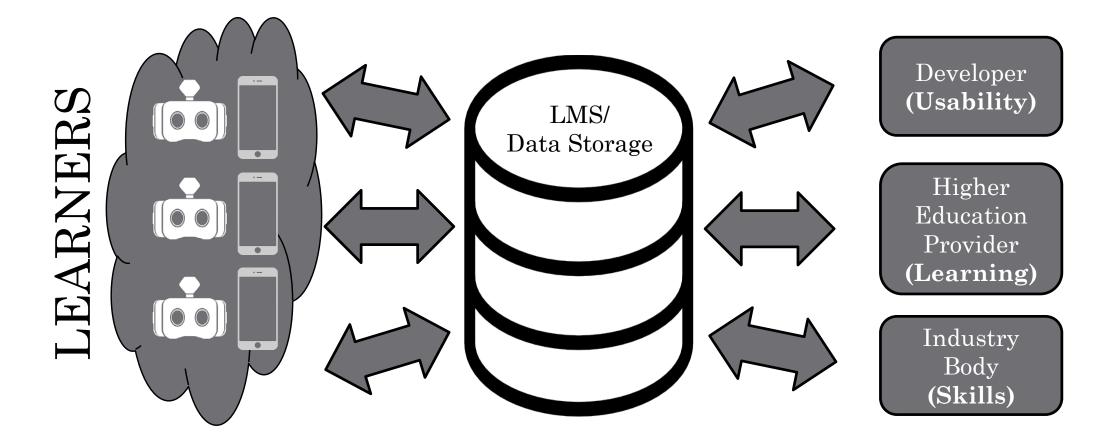


# Analytics: Capture learner <> mixed reality material interaction(s) and learning outcomes

	Past	Present	Future		
Information	What happened? (Reporting)	What is happening now? (Alert)	What will happen? (Extrapolation)		
Insight	How and did it happen? (modelling, experimental design)	What's the next best action? (Recommendation)	What's the best/worst that can happen? (prediction, optimisation, simulation)		
Davennort et al (2010)					

Davenport et al., (2010)

### Model



[BYOD Mixed Reality Simulation Pedagogy] <u>Learning Outcomes + Spatial</u> <u>Interaction Data</u> [Evidence] <u>Analytics + Visualisation(s)</u>

### Simulation Construction Tools

- Unity3d game engine (<u>www.unity3d.com</u>)
- Vuforia augmented reality plugin (<u>www.vuforia.com/</u>)
- MySQL (<u>www.mysql.com/</u>)
- Php (<u>secure.php.net/</u>)
- Google Cardboard headset (<u>vr.google.com/cardboard/</u>)



## Introductory AR in Unity3d using Vuforia

→ Beginners Guide Only using a single image target

Dr James Birt

tinyurl.com/IntroUnityAR

### Vuforia with Multitargets for AR/VR $\rightarrow$ Allows 360<sup>o</sup> physical rotation

- <u>developer.vuforia.com</u>
- Signup
- Downloads > Samples > Digital Eyewear > Unity3d: AR/VR Sample scene
- Develop > License Manager > Add License Key
- Develop > Target Manager > Add Database
- Develop > Target Manager > [DBName] > Add Target(s) - this example uses six (6)
- Develop > Target Manager > [DBName] > Download Database



Shown is a 6cm<sup>3</sup> marker – which will allow solid tracking @ 40-50 cm the theoretical suggestion is 1cm (marker size) for 10cm distance but practice is more like 7cm distance. This can be improved using polypropylene paper which absorbs light. I also recommend 5 star image markers.



#### brosvision.com/ar-marker-generator/

### Unity3d

- Download Unity3d
- Create new Project

Projects

- Import Digital Eyewear Scene
- Import Image Database

Getting started

Project name*	
ARDEMO	
Location*	
F:\Unity	
<b>3D</b> 2D	Cancel Create project
Asset packages	ounder project

## Everything you need to succeed in games and VR/AR

Welcome to one of the world's largest creative communities -- and the number one game development platform. Unity gives you everything you need to realize your creative vision fast, and move ahead.

Get Unity now

What is Unity?

Personal

All the features for beginners & hobbyists to get started. Learn more

unity3d.com/

Free No credit card required

Download now

### AR Camera (Vuforia Behaviour)

- Click the ARCamera and view the inspector window
- Vuforia Behaviour (Script) copy your license key to the Vuforia Behaviour Script App License Key
- Switch the <u>Camera Device Mode</u> to MODE\_OPTIMIZE\_SPEED – this will help with real-time image movement & pickup
- For now I will leave Tracked Images & Objects at one (1) but if you want to track multiple targets you will need to modify this number
- Please note: Even though we are using a Multi target marker we are only ever tracking one (1) target at a time

▼ 📴 ⊽ Vuforia Behaviour (Script) Script	😰 VuforiaBehaviour	<ul> <li>Image: Second second</li></ul>
App License Key	*****	vv
	xxxxxxxxxxxxxxxxx	XΧ
	XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	XΧ
	*****	ΧX
Camera Device Mode	MODE_OPTIMIZE_SPEED	÷ 1
Max Simultaneous Tracked Images Max Simultaneous Tracked Objects		
Load Object Targets on Detection	- m	
Camera Direction	CAMERA_DEFAULT	÷1
Mirror Video Background	DEFAULT	\$
World Center Mode	CAMERA	ŧ)
🕨 健 🗸 Digital Eyewear Behaviour	(Script)	<b>R</b> \$,
🕨 📴 🔽 Default Initialization Error	Handler (Script)	🗑 🌣,
🕨 健 🔽 Database Load Behaviour (	(Script)	2 *,
🕨 健 🔽 Video Background Manage	r (Script)	🔊 🌣,
🕨 健 🔽 Smart Terrain Tracker Beh	aviour (Script)	10 \$,
🕨 健 🔽 Device Tracker Behaviour		
🕨 🛃 🔽 Web Cam Behaviour (Scrip		P \$.
🕨 🤂 Keep Alive Behaviour (Scri	pt)	2.
▶ 📴 Reticle (Script)		<b>R</b> \$,
▶ 📴 🗸 VR Input (Script)		<b>A</b> ,
▶ 📴 🗸 VR Eye Raycaster (Script)		
▶ 🔂 🗸 Autofocus (Script)		121 Sty
▶ 🖪 🔽 Login (Script)		121 SP-
► ► Control (Script)		10 47.
► 📴 🗸 HS Controller (Script)		10 XT
▶ 🖪 🗸 Hide Video Feed (Script)	(4a)	
🕨 🖪 🔽 Billboard Annotations (Scr	(pt)	101 201

### AR Camera (Digital Eyewear)

- For this example we are using a generic Google Cardboard
- This method uses a video see-through method using your BYOD mobile phone

👍 🔽 Digital Eyewear Behaviou		
	🖻 DigitalEyewearBehaviour	
Eyewear Type	Video See-Through	
Stereo Camera Config	Vuforia	
Viewer Type	Generic Cardboard (Vuforia)	
Button Type	BUTTON_TYPE_MAGNET	
Screen To Lens Distance	0.042	
Inter Lens Distance	0.06	
Tray Alignment	TRAY_ALIGN_BOTTOM	
Lens Center To Tray Distance	0.035	
Distortion Coefficients	0.441 0.156	
Field Of View	40 40 40 40	
Contains Magnet	True	

<u>library.vuforia.com/articles/Training/</u> <u>Vuforia-for-Digital-Eyewear</u>



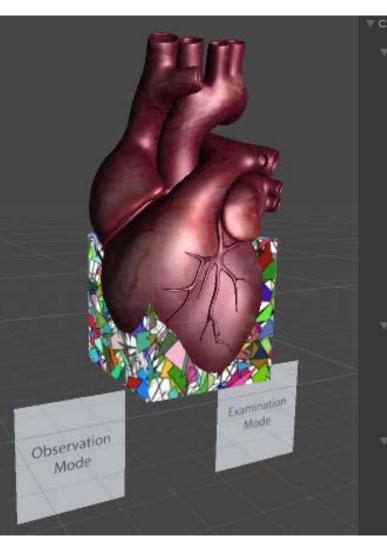
### AR Camera (Database Load)



```
<?xml version="1.0" encoding="UTF-8"?>
<QCARConfig>
    <Tracking>
       <ImageTarget name="CubeMRMarker.Right" size="6.000000 6.000000"/>
       <ImageTarget name="CubeMRMarker.Top" size="6.000000 6.000000"/>
       <ImageTarget name="CubeMRMarker.Front" size="6.000000 6.000000"/>
       <ImageTarget name="CubeMRMarker.Back" size="6.000000 6.000000"/>
       <ImageTarget name="CubeMRMarker.Bottom" size="6.000000 6.000000"/>
       <ImageTarget name="CubeMRMarker.Left" size="6.000000 6.000000"/>
       <MultiTarget name="CubeMRMarker">
            <Part name="CubeMRMarker.Left" translation="-3.0 0 0" rotation="AD: 0 1 0 -90"/>
            <Part name="CubeMRMarker.Right" translation="3.0 0 0" rotation="AD: 0 1 0 90"/>
            <Part name="CubeMRMarker.Front" translation="0 0 3.0" rotation="AD: 1 0 0 0"/>
            <Part name="CubeMRMarker.Back" translation="0 0 -3.0" rotation="AD: 0 1 0 180"/>
            <Part name="CubeMRMarker.Top" translation="0 3.0 0" rotation="AD: 1 0 0 -90"/>
            <Part name="CubeMRMarker.Bottom" translation="0 -3.0 0" rotation="AD: 1 0 0 90"/>
        </MultiTarget>
    </Tracking>
</QCARConfig>
```

### Add AR/VR asset(s) to scene

- Drag an instance of the MultiTarget prefab into your scene – rename e.g. CubeMarker
- Set your ChildTargets to each of your Image Markers from your database – turn off mesh renderer – you don't want to see the cube
- Place your 3d model onto your marker and make it a child
- Add any 3d spatial GUI elements to your marker



🔻 CubeMarker 🛡 Heart AorticArch InferiorVenaCava LeftAtrium LeftPulmonaryArtery LeftPulmonarvVeins PulmonaryTrunk RightPulmonaryArtery RightPulmonaryVeins RightVentricle ▼ cubeGUI observationModeButton examinationModeButton ChildTargets CubeMRMarker.Left CubeMRMarker.Right CubeMRMarker.Front CubeMRMarker.Back CubeMRMarker.Top CubeMRMarker.Bottom

# Simulation Breakdown

### • Display login GUI

- Allow login entry in this demo we allow all logins (for authentication you would query your user database)
- Record details
- On successful Login Display marker

PLACE AR CUBE

IN FRONT OF CAMERA

instructions



MR

Heart

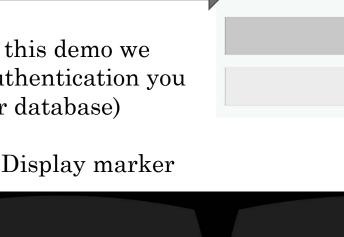
1234

Login

MR

Heart

Enter User ID



# $\rightarrow$ Login

' loginGUI 🔻 login

whiteBackground

Placeholder

login

login

id

instructionsLEFT 🐨 instructionsRIGHT

InputField (InputField)

heartMRImg

Text

Text

▼ presentMarker

EventSystem

✓ ARCamera 📙 🔽 Login (Script)

Instructions LEFT

User ID Field

Instructions RIGHT

User ID Login UI

Cube

▼ InputField

▼ Button

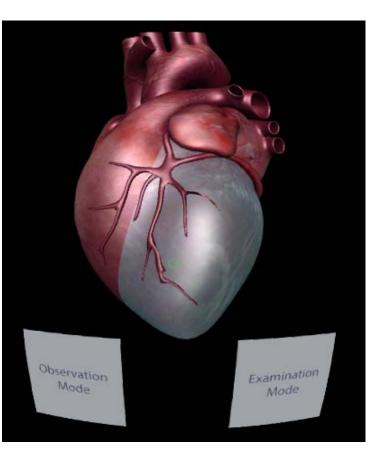
### Simulation Breakdown → Main Menu

🗸 cubeGUI

observationModeButton
examinationModeButton

👕 🗸 ARCamera		
🔻 🖪 🔽 Hide Vide	eo Feed (Script)	2
Script	🖸 hideVideoFeed	
Heart	📑 id	
Video Feed	📑 BackgroundPla	an
Video Feed Enab	oled 🥅	
🔻 🖪 🔽 Control (	Script)	9
Script	🛄 control	
Current Selectio	n 💦 Left Ventricle	
Marker	🐨 CubeMarker	

When marker found - switch off camera feed to focus user attention ... user(s) virtual arm has been established with the AR setup. The marker is still tracked in real-time but distraction is reduced.

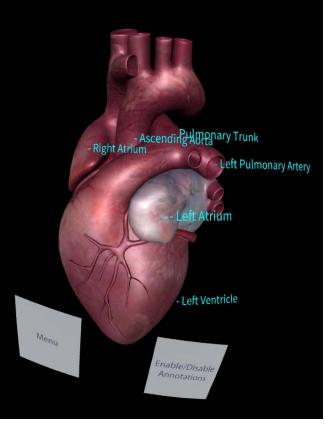


- Turn off Login & Marker display GUI
- Turn on Spatial GUI Menus Learner Observation Mode & Examination Mode

### Simulation Breakdown → Learner Observation Mode

enableDisableAnnotation	🖪 🔽 Billboard A	nr	iotations (Scri
menuButton			🗈 billboardAnnoi
annotations	Main Camera		Sphere
	Heart		id
▶ annotation	Disabled Text		
▶ annotation (1)	Annotation Array		
▶ annotation (2)	Size		
▶ annotation (3)	Element 0		🐨 annotation
▶ annotation (4)	Element 1		annotation (1)
	Element 2		annotation (2)
▶ annotation (5)	Element 3		📬 annotation (3)
▶ annotation (6)	Element 4		🗊 annotation (4)
▶ annotation (7)	Element 5		annotation (5)
▶ annotation (8)	Element 6		🗊 annotation (6)
▶ annotation (9)	Element 7		🐨 annotation (7)
	Element 8		🐨 annotation (8)
▶ annotation (10)	Element 9		annotation (9)
▶ annotation (11)	Element 10		🗊 annotation (10
▶ annotation (12)	Element 11		ᄛ annotation (11
▶ annotation (13)	Element 12		🐨 annotation (12
▶ annotation (14)	Element 13		annotation (13
▶ annotation (15)	Element 14		🗊 annotation (14
	Element 15		🐨 annotation (19
▶ annotation (16)	Element 16		📽 annotation (16

As the user physically moves the cube (or their head) annotations become visible. The user can also highlight elements of the model by focusing the reticule over the mesh object. This establishes a spatial connection to the user. The user can turn on or off annotations by focusing the reticule over the menu items.

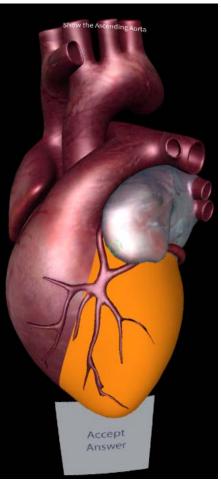


- Turn off Spatial GUI Menus Learner Observation Mode & Examination Mode
- Turn on Annotation (on/off) Mode This allows for user(s) formative learning

### Simulation Breakdown → Learner Examination Mode

Is I Control (Script)	8
Current Selection	CaleftVentricle
	🔹 CubeMarker
Questions Array	
Element 0	Show the Ascending Aorta
Element 1	Show the left Common Carotid Artery
Element 2	Show the Right Atrium
Element 3	Show the Left Pulmonary Veins
Element 4	Show the Inferior Vena Cava
Model Segment Array	
	5
Element 0	S AscendingAorta
Element 1	LeftCommonCarotidArtery
Element 2	嘴 RightAtrium
Element 3	CLeftPulmonaryVeins
Element 4	😘 Inferior Vena Cava
Current Question	
Current Answer	S Left Ventricle
Time Per Question	12.25773
	{LeftVentricle,
Data Timer	0.0213742
	(3.3, -3.8, -8.4),(3.3, -3.8),(
Magnitude	9.777357,9.776716,9.778387,9.776955,9.775885,9.780875,9.781712,9.
	(0.2, 0.1, 0.0, -1.0),(0.2, 0.1, 0.0, -1.0),(0.2, 0.1, 0.0, -1.0),(0.2, 0.1, 0

- Questions are randomised in this case five (5) sample questions
- As the user selects answers these are added to the mesh array for later storage – we record all focused meshes to record how the user interacts (e.g. confusion/uncertainty
  - flipping between meshes)
- A timer is recorded per question
- Spatial 3d data is recorded 24x/s to allow for observation replay
- Direction:  $\{X, Y, Z\}$  cube translation
- Magnitude: cube distance to camera
- Quaternion: {X,Y,Z,w} cube rotation



## Simulation Breakdown → Data (Analytics) Storage

🔻 健 🗸 HS Controller (Script)		<b>a</b> \$,
	🖻 HSController	0
Send		
Add Score URL	http://www.mixedrealityresearch.com/	PHP FILE
User ID	userID	
Questions	questions	
Answers	answers	
Time	time	
Mesh	mesh	
Direction	direction	
Magnitude	magnitude	
Quaternion	quaternion	

- Create unity WWWForm();
- Add fields using form.AddField();
- \$Post URL/phpfile using WWW(URL, form);
- phpfile: create timestamp: date('Y-m-d H:i:s'); & update database for the example this is hardcoded you should check authentication
- Wait for write confirmation & send back to Unity
- You should also use a hashing function (e.g. MD5) to improve security NOT done for this example
- Note: Formative observations are currently NOT recorded for data analytics only exams

#### Log attemptID (primary key) timestamp (server time) user (login details) questions (random Q order) answers (T/F) time per question mesh focus per question direction $\{x,y,z - translation\} 24x/s$ magnitude $\{d - camera \ distance\} 24x/s$ Quarternion $\{x,y,z,w - rotation\} 24x/s$ Great Tutorial on server side storage: wiki.unity3d.com/index.php?title=Server\_Side\_Highscores

## Dashboard

- At present the dashboard is a listing of all recorded actions from the SQL database using a php file
- The ultimate aim of the dashboard is to allow an [observer] to:
  - List all users that have/have not completed the simulation pedagogy
  - Check [learner] answers & method/time in answering
  - Search for a [learner] and [observe] (replay) their attempt using the recorded 3d spatial data [translation, distance and rotation]

Timestamp	User	Questions	Answer/Question	Time/Question	MeshSelected/Question
2016-11-17 07:48:22	12345	0,1,2,3,4,	F,F,F,F,F,	7.238323,5.628466,6.615757,6.550018,7.38278,	{LeftVentricle,},{LeftAtrium,},{PulmonaryTrunk,},{AorticArch,}
2016-11-17 08:03:56	98765	0,1,2,3,4,	F,T,F,F,F,	8.304294,12.31514,14.63738,8.455581,7.206904,	$[LeftVentricle,], \{PulmonaryTrunk, AorticArch, AscendingAorta, \}, \{SuperiorVenaCava, RightVentricle, LeftAtrium, \}, \{LeftCommonCarotidArtery, \}, \{BrachiocephalicTrunk, \}, \{PulmonaryTrunk, AorticArch, AscendingAorta, \}, \{SuperiorVenaCava, RightVentricle, LeftAtrium, \}, \{LeftCommonCarotidArtery, \}, \{BrachiocephalicTrunk, \}, \{PulmonaryTrunk, AorticArch, AscendingAorta, \}, \{SuperiorVenaCava, RightVentricle, LeftAtrium, \}, \{LeftCommonCarotidArtery, \}, \{BrachiocephalicTrunk, \}, \{PulmonaryTrunk, AorticArch, AscendingAorta, \}, \{SuperiorVenaCava, RightVentricle, LeftAtrium, \}, \{LeftCommonCarotidArtery, \}, \{BrachiocephalicTrunk, \}, \{PulmonaryTrunk, AorticArch, AscendingAorta, \}, \{SuperiorVenaCava, RightVentricle, LeftAtrium, \}, \{LeftCommonCarotidArtery, \}, \{BrachiocephalicTrunk, \}, \{PulmonaryTrunk, AorticArch, AscendingAorta, \}, \{SuperiorVenaCava, RightVentricle, LeftAtrium, \}, \{LeftCommonCarotidArtery, \}, \{BrachiocephalicTrunk, \}, \{PulmonaryTrunk, AorticArch, AscendingAorta, \}, \{SuperiorVenaCava, RightVentricle, LeftAtrium, \}, \{PulmonaryTrunk, AorticArch, AscendingAorta, \}, \{PulmonaryTrunk, AorticArch, AscendingAorta, \}, \{SuperiorVenaCava, RightVentricle, LeftAtrium, \}, \{PulmonaryTrunk, AorticArch, AscendingAorta, \}, \{PulmonaryTrunk, \}, \{PulmonaryTr$
2016-11-21 07:57:49	123456	0,1,2,3,4,	F,F,F,F,F,	8.632071,5.898353,17.11287,8.905243,8.231584,	{LeftVentricle,LeftAtrium,},{LeftAtrium,},{AorticArch,LeftAtrium,},{leftSubclavianArtery,},{BrachiocephalicTrunk,}
2016-11-21 10:23:36	1234567	0,1,2,3,4,	F,F,F,F,F,	7.009307,9.827247,6.01168,6.281147,6.727718,	{PulmonaryTrunk,}, {leftSubclavianArtery,}, {RightVentricle,}, {LeftPulmonaryArtery,}, {RightVentricle,}
2016-11-22 01:12:11	123456	0,1,2,3,4,	T,F,F,F,F,	27.87911,8.705873,20.59627,7.321079,8.006312,	{RightVentricle,RightAtrium,LeftPulmonaryVeins,},{RightVentricle,},{PulmonaryTrunk,LeftAtrium,},{AscendingAorta,},{LeftVentricle,}
2016-11-22 05:47:45	12345	0,1,2,3,4,	F,F,F,F,F,	12.61238,6.670756,7.058633,14.89314,6.949143,	{PulmonaryTrunk,RightVentricle,},{PulmonaryTrunk,},{RightAtrium,},{LeftVentricle,},{PulmonaryTrunk,}

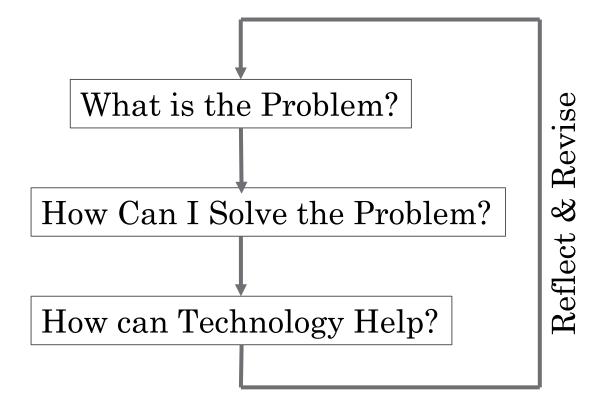
Over the past year, the continue

141 ADVICOL 20184A

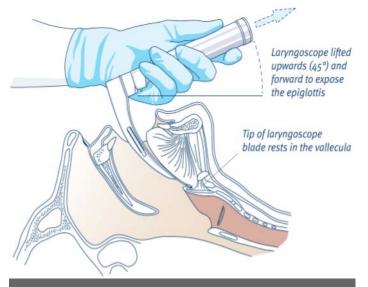
#### Technology just part of the class bled classroom'," he said. Dr

Cowling said the trend towards came more a part of students' ADOPTING technology in technology-led pedagogy lives, with one study indicating needed to be replaced instead the classroom should just be a a "near ubiquitous" level of acwith pedagogy-led technology. part of the learning process, an cess to mobile phones or com-This acknowledged that puters, and another showing academic from Queensland's learing was the most import-86 per cent of students pre-CQUniversity says. ord using the internet to ant part of education. Cowling has awling will Dr Mie (2)r at the Interportin written a re Associwhich he ...... pre Education in Adelaide, suggesting it was adopted III national New Australia of chalkotter to sto) thinking about whiteboards instead and Student Services Asation d o disital p sectors i verhe of by teachers to view it as just part spend to y ars ing about a 'whiteboard-led the today until Friday. TIMO important as technology becampended and the salution of the sa

## Pedagogy before technology



#### Paramedic Distance Education: The Problem



**Traditional Teaching Method** 



"this course is a 'skills' learning course ... there should be a way for us to actually get more time doing skills ... distance students at a severe disadvantage ... I am missing out ... you can read about the skills but its impossible to get feedback and to know if you're doing it right ... no substitution for experience ... any software or equipment to at least go through the motions of doing the skills?" Paramedic Student Learner(s) (201x-2014)

### Paramedic Distance Education: Solving

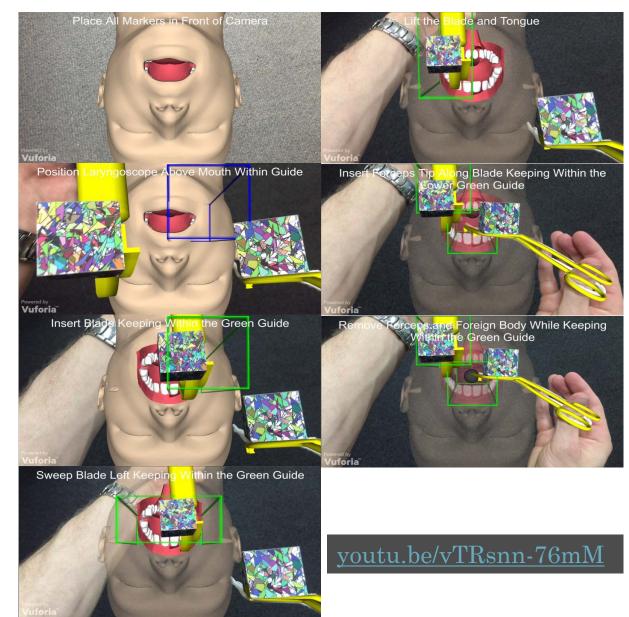


- [Discipline expert] we need every student to have a portable airways mannequin & cheap tools to practice the skills but cost is prohibitive ... residential schools work ... but not held early enough for students
- [Mixed Reality Team] tools could be provided to students by 3D printing them (cost/set) ~ \$1 AUD + postage
- [Mixed Reality Team] Airways mannequin could be simulated virtually using a mobile phone
- [Discipline expert] students would need both hands free, so the phone would need to be mounted in their eyeline
- [Mixed Reality Team] we can provide a hat and 3d printed hat mount
- [Mixed Reality Team] A simulation app can then be constructed using a free game engine [Unity3d] that could observe and monitor [learner] skills

### Paramedic Distance Education: Technology V1



mapping of the skills -• • -ದ Need to create



42

#### Paramedic Distance Education: Reflection

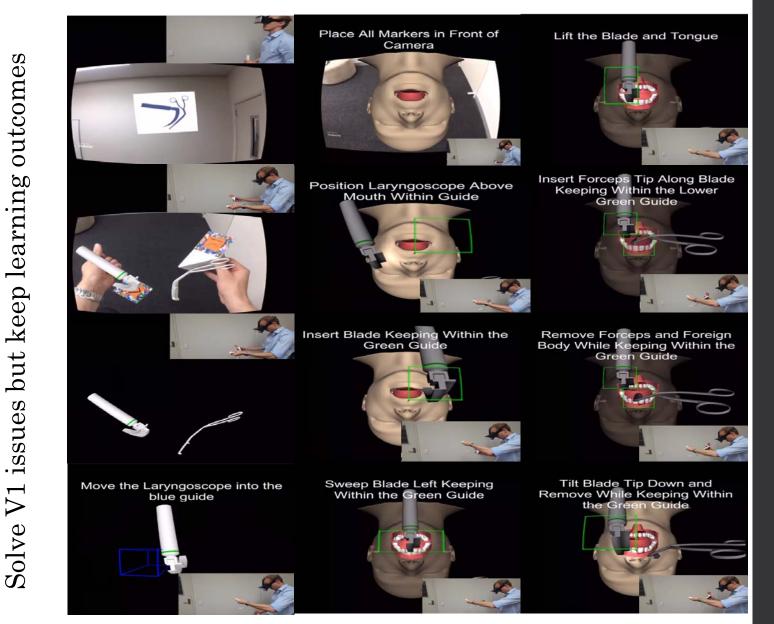
- [Learners] were very excited ... [practice] the skills at home ... [learner] more involved in the course & less isolated
- [Observers] found most [learners] struggled with the setup of the equipment & progression through the required steps ... especially when introducing the Magill forceps & removing the foreign body
- [Learners] commented "my hands seem to pass by the [simulated airways manikin]" ... "spent too much time focusing on the markers & not on the [simulated airways manikin] ... resulting in frustration when the simulation would present red boxed & restart
- Many [learners] commented that they did not get around to using the [simulation] highlighting time struggles and being "extra" work
- [Head Paramedic] on reflection should have encouraged more frequent use of the simulation with a reminder & linkage to the learning tasks

#### Paramedic Distance Education: Revision

Solve V1



youtu.be/wIfwZFKlSQU



## Augmented Augmented Real Virtual Environment Concept mapping a Environment mixed reality pedagogy pilot study

Tangible User Interface







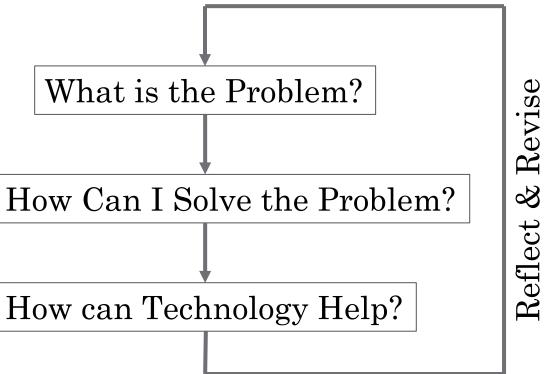


## Let's Talk About You.

• How does this work for you in your classroom?

How Can I Solve the Problem?

• Remember, **PEDAGOGY** before TECHNOLOGY



# Let's Talk About You→ What is the Problem?

- Start with your learning outcomes:
  - Which ones do students struggle with?
  - How do they struggle with them?
  - What do you think the problem is?
- Take 5 minutes to think of the most difficult problem students face in one of your classes, then we will ask a few people in the audience to share

• You can discuss with your table group if you'd like

## Let's Talk About You → How Can I Solve the Problem?

- Pick a small problem to solve (can't solve the whole semester at once)
  - {Pretend you have a wand} → If [you] could do anything, what would help solve this problem?
- Take 5 minutes to write down the solution
- Remember there are no limits here, let your mind run free with whatever approach you think would best solve this problem you have
- Again, feel free to work with your table group on this

## Let's Talk About You → How can Technology Help?

- Can you do that lesson right now? How would you do it?
- Could technology help with that lesson? → Think about the cases we presented
- Make sure you keep the purpose in mind, what is the lesson trying to teach, what do the students struggle with, and how does your method help with that outcome
- Take 5 minutes to come up with a solution that you think might work

## Workshop Conclusion Survey

Mixed Reality in Higher Education: Pedagogy Before Technology - Workshop Feedback Survey Presenters: Dr James Birt (Bond University) & Dr Michael A. Cowling (CQUniversity)

Thank you for participating. Your feedback on the experience, process and content is always appreciated.

QUESTIONS (Please cross the most appropriate response) - Likert Scale 1 - 5 - use (0) for N/A, (1) for strongly disagree and (5) for strongly agree										
Was the workshop content relevant?				3	4	5				
Was the workshop content comprehensive?			2	3	4	5				
Was the workshop content easy to understand?				3	4	5				
Did you find the workshop well-paced?			2	3	4	5				
Did you find the workshop engaging and interactive?		1	2	3	4	5				
Did the workshop contain a good mix of listening and discussion?		1	2	3	4	5				
Were the facilitators knowledgeable?		1	2	3	4	5				
Were the facilitators well prepared?		1	2	3	4	5				
Where the facilitators responsive to questions?		1	2	3	4	5				
Did you find the activities useful learning experiences?		1	2	3	4	5				
Overall how satisfied were you with this workshop?			2	3	4	5				
Additional Comments										

50